

9 - Conditional density

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- Independence
- Adding independent random variables
- Uncorrelated Gaussians
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Conditioning

- Given a joint pdf $p(x, y)$ on \mathbb{R}^2
- Measure y ; we would like to find the conditional pdf of x

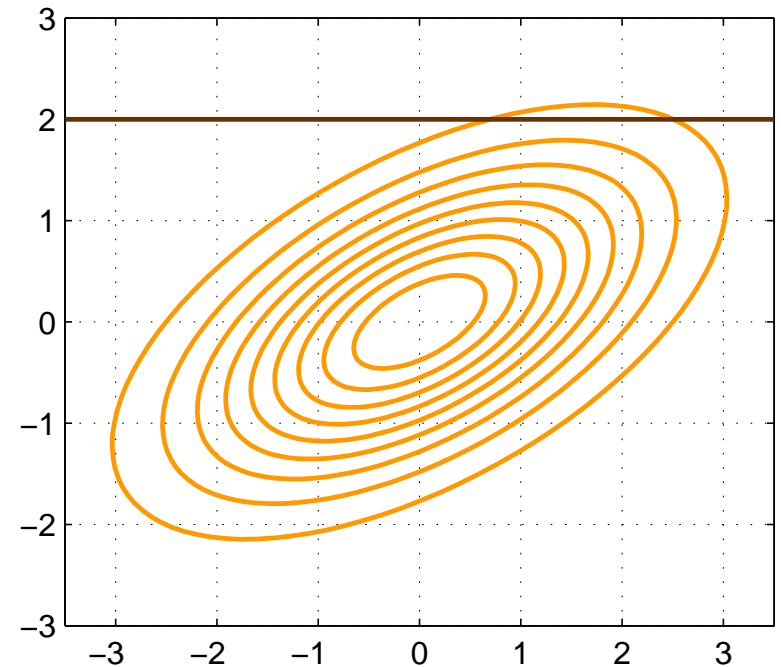
Frequency Interpretation

- Collect data (x, y)
- Discard those pairs with

$$y \notin [y_{\text{meas}}, y_{\text{meas}} + \varepsilon]$$

for small $\varepsilon > 0$

- Then the density of x will approximate the conditional pdf



Conditioning

We would like to define the conditional probability

$$\mathbf{Prob}(A \mid B) = \frac{\mathbf{Prob}(A \cap B)}{\mathbf{Prob}(B)}$$

where

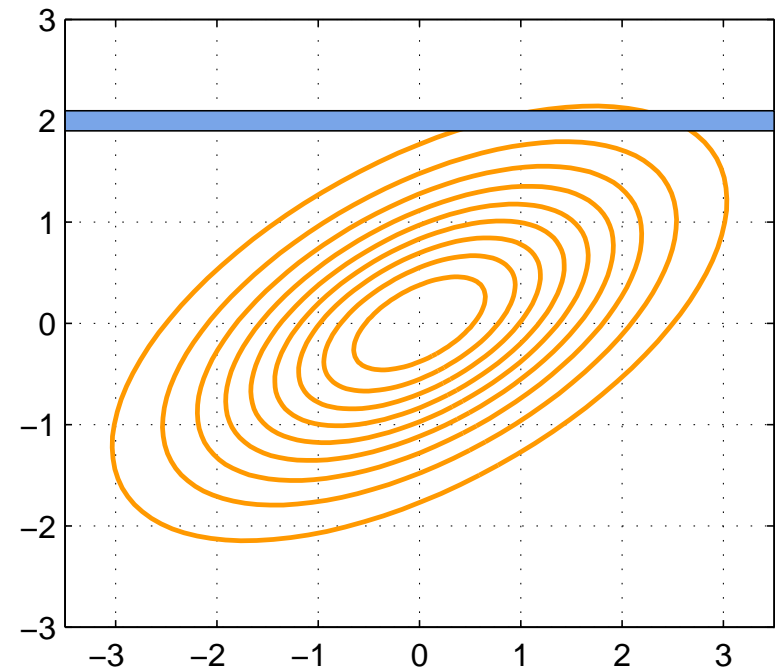
$$A = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \mid x \in [a_1, a_2] \right\} \quad B = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \mid y = y_{\text{meas}} \right\}$$

We cannot do this, since $\mathbf{Prob}(B) = 0$.

Instead we look at

$$B_\varepsilon = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \mid y \in [y_{\text{meas}}, y_{\text{meas}} + \varepsilon] \right\}$$

and take the limit as $\varepsilon \rightarrow 0$



Conditional pdf as a limit

$$\mathbf{Prob}(A \mid B) = \lim_{\varepsilon \rightarrow 0} \mathbf{Prob}(A \mid B_\varepsilon)$$

$$= \lim_{\varepsilon \rightarrow 0} \frac{\int_{y_{\text{meas}}}^{y_{\text{meas}}+\varepsilon} \int_{a_1}^{a_2} p(x, y) dx dy}{\int_{y_{\text{meas}}}^{y_{\text{meas}}+\varepsilon} \int_{-\infty}^{\infty} p(x, y) dx dy}$$

$$= \lim_{\varepsilon \rightarrow 0} \frac{\varepsilon \int_{a_1}^{a_2} p(x, y_{\text{meas}}) dx + \text{terms of order } \varepsilon^2 \text{ or higher}}{\varepsilon \int_{-\infty}^{\infty} p(x, y_{\text{meas}}) dx + \text{terms of order } \varepsilon^2 \text{ or higher}}$$

$$= \int_{a_1}^{a_2} \frac{p(x, y_{\text{meas}})}{p^y(y_{\text{meas}})} dx$$

where p^y is the marginal pdf of y .

Conditional pdf

We write this as

$$\mathbf{Prob}(x \in [a_1, a_2] \mid y = y_{\text{meas}}) = \int_{a_1}^{a_2} \frac{p(x, y_{\text{meas}})}{p^y(y_{\text{meas}})} dx$$

We define the conditional pdf $p^{x|y}$ of x given $y = y_{\text{meas}}$ by

$$\mathbf{Prob}(x \in [a_1, a_2] \mid y = y_{\text{meas}}) = \int_{a_1}^{a_2} p^{x|y}(x, y_{\text{meas}}) dx$$

Since this holds for all a_1, a_2 , we must have

$$p^{x|y}(x, y_{\text{meas}}) = \frac{p(x, y_{\text{meas}})}{p^y(y_{\text{meas}})}$$

Again, we can think of the denominator as simply normalizing the pdf.

Conditional mean and covariance

The *conditional mean* of x given y is

$$\mathbf{E}(x \mid y = y_{\text{meas}}) = \int x p^{|y}(x, y_{\text{meas}}) dx$$

This is a *function of y_{meas}*

The *conditional covariance* of x given y is

$$\mathbf{cov}(x \mid y = w) = \mathbf{E}\left(\left(x - f(w)\right)\left(x - f(w)\right)^T \mid y = w\right)$$

Here $f(w) = \mathbf{E}(x \mid y = w)$. The conditional covariance is also a function of y_{meas}

Conditional notation

- conditional expectation defines a function; e.g.,

$$f(w) = \mathbf{E}(x \mid y = w)$$

defines a function $f : \mathbb{R}^m \rightarrow \mathbb{R}^n$

- We often take expectations of the form

$$\mathbf{E}(f(y))$$

For the above f we have $\mathbf{E}(f(y)) = \mathbf{E} x$

- This is often written

$$\mathbf{E}(\mathbf{E}(x \mid y))$$

Conditional notation

- Another common notation

$$h(w) = \mathbf{cov}(x \mid y = w)$$

- Again, you see

$$\mathbf{E} \text{ trace } \mathbf{cov}(x \mid y)$$

which means $\mathbf{E} \text{ trace}(h(y))$

Conditional pdf for a Gaussian

Suppose $x \sim \mathcal{N}(0, \Sigma)$, and

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \Sigma = \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}$$

Suppose we measure $x_2 = y$. We would like to find the conditional pdf of x_1 given $x_2 = y$

- Is it Gaussian?
- What is the *conditional mean* $\mathbf{E}(x_1 | x_2 = y)$ of x_1 given x_2
- What is the *conditional covariance* $\mathbf{cov}(x_1 | x_2 = y)$ of x_1 given x_2 ?

Conditional pdf for a Gaussian

The pdf of x is

$$p^x(x) = c_1 \exp\left(-\frac{1}{2}x^T \Sigma^{-1}x\right)$$

By the completion of squares formula

$$\Sigma^{-1} = \begin{bmatrix} I & 0 \\ -\Sigma_{22}^{-1}\Sigma_{21} & I \end{bmatrix} \begin{bmatrix} (\Sigma_{11} - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21})^{-1} & 0 \\ 0 & \Sigma_{22}^{-1} \end{bmatrix} \begin{bmatrix} I & -\Sigma_{12}\Sigma_{22}^{-1} \\ 0 & I \end{bmatrix}$$

Hence

$$x^T \Sigma^{-1}x = (x_1 - Lx_2)^T T^{-1}(x_1 - Lx_2) + x_2^T \Sigma_{22}^{-1}x_2$$

where

$$T = \Sigma_{11} - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21} \quad L = \Sigma_{12}\Sigma_{22}^{-1}$$

Conditional pdf for a Gaussian

The conditional pdf of x_1 given x_2 is therefore

$$\begin{aligned} p^{x_2}(x_1, y) &= \frac{c_1}{p^{x_2}(y)} \exp\left(-\frac{1}{2}(x_1 - Ly)^T T^{-1}(x_1 - Ly) - \frac{1}{2}y^T \Sigma_{22}^{-1}y\right) \\ &= \frac{c_1}{p^{x_2}(y)} \exp\left(-\frac{1}{2}y^T \Sigma_{22}^{-1}y\right) \exp\left(-\frac{1}{2}(x_1 - Ly)^T T^{-1}(x_1 - Ly)\right) \end{aligned}$$

Hence $p^{x_2}(x_1, y)$ is *Gaussian*

$$p^{x_2}(x_1, y) = c_2(y) \exp\left(-\frac{1}{2}(x_1 - Ly)^T T^{-1}(x_1 - Ly)\right)$$

where $c_2(y)$ is such that $\int p^{x_2}(x_1, y) dx_1 = 1$

Conditional pdf for a Gaussian

- If $x \sim \mathcal{N}(0, \Sigma)$, then the conditional pdf of x_1 given $x_2 = y$ is *Gaussian*
- The *conditional mean* is

$$\mathbf{E}(x_1 | x_2 = y) = \Sigma_{12}\Sigma_{22}^{-1}y$$

It is a *linear function* of y

- The *conditional covariance* is

$$\mathbf{cov}(x_1 | x_2 = y) = \Sigma_{11} - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21}$$

It is *not* a function of y

Conditional pdf for a Gaussian

- Here

$$\mathbf{cov}(x) = \begin{bmatrix} 2 & 0.8 \\ 0.8 & 1 \end{bmatrix}$$

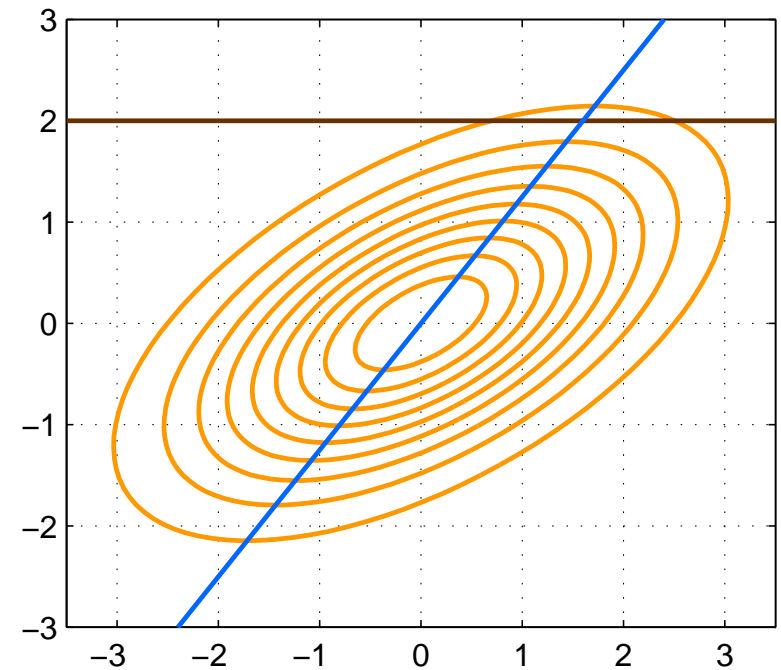
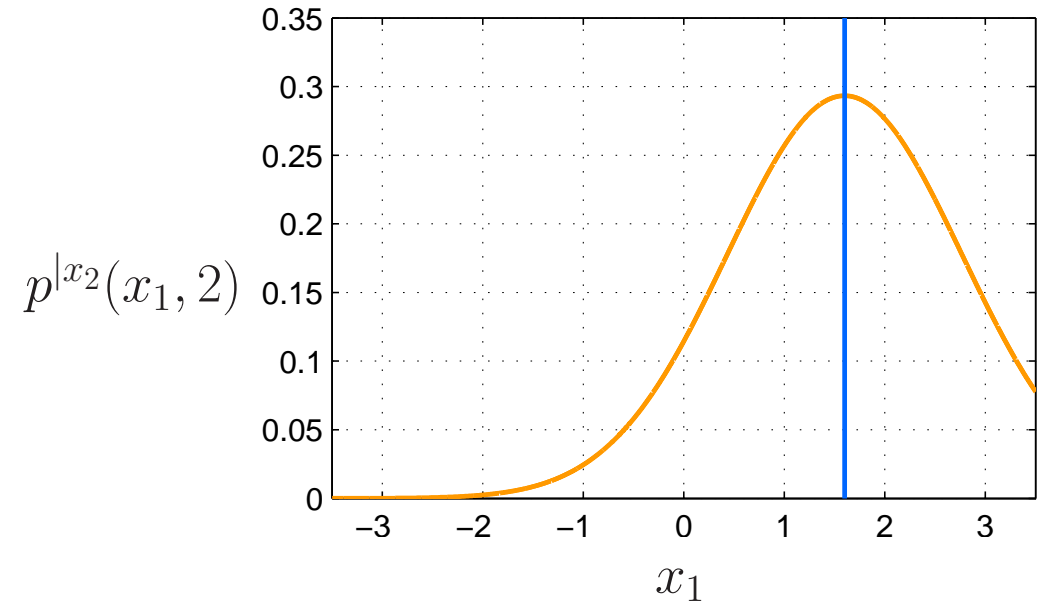
- We have

$$L = 0.8 \quad T = 1.36$$

- Hence

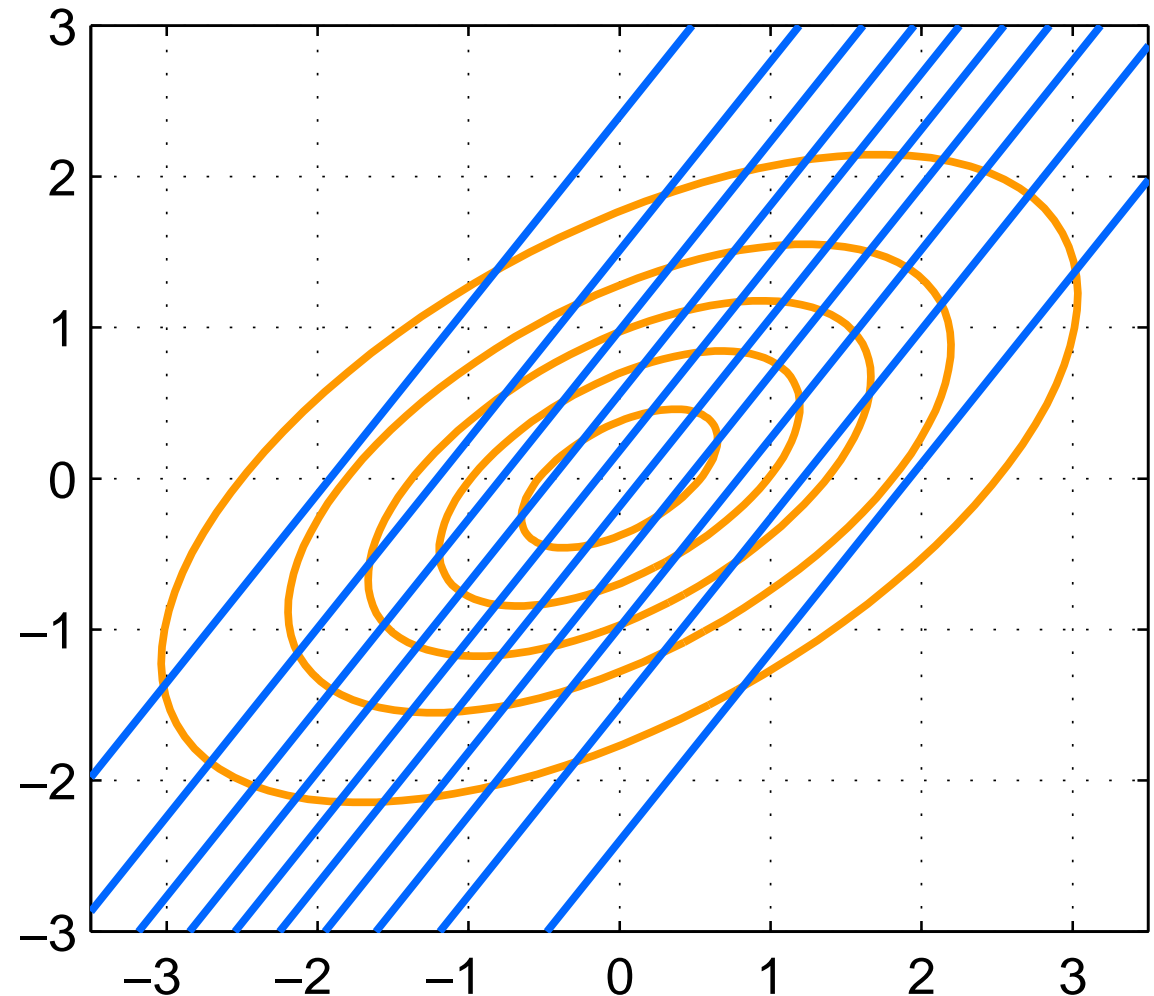
$$\mathbf{E}(x_1 \mid x_2 = 2) = 1.6$$

$$\mathbf{cov}(x_1 \mid x_2 = 2) = 0.8$$



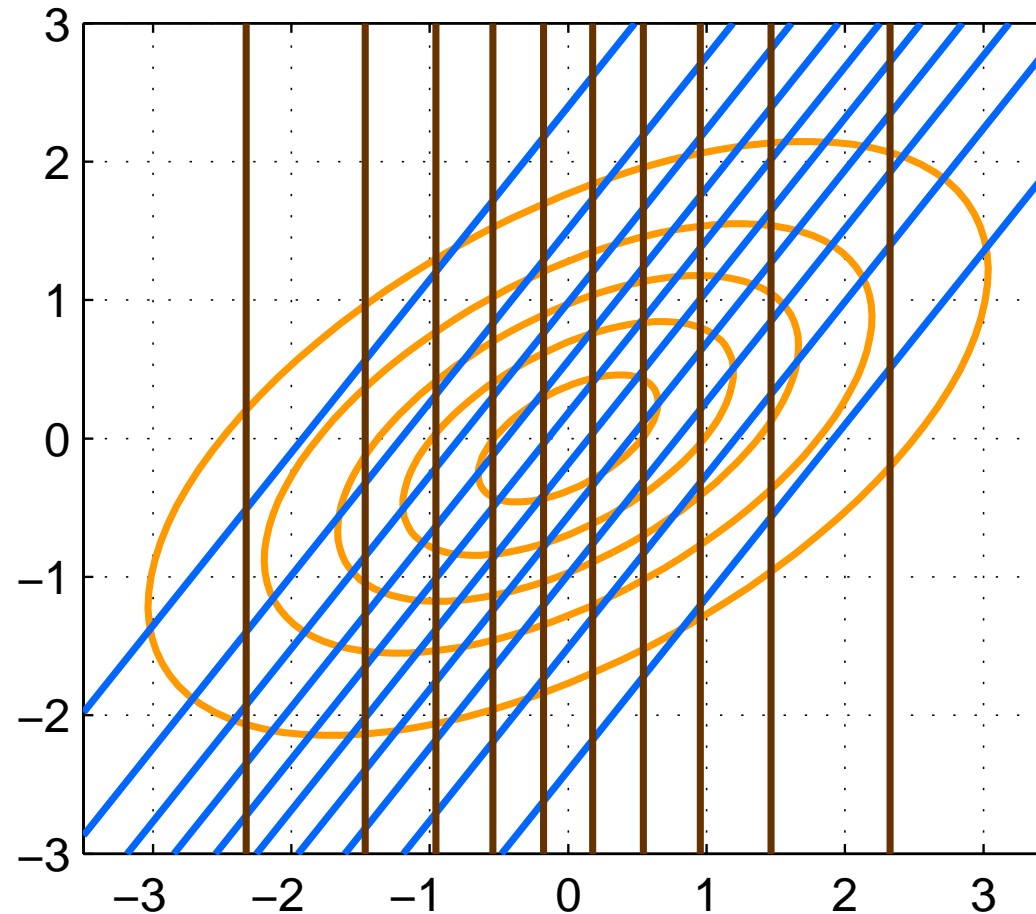
Conditional pdf for a Gaussian

- Here $\Sigma = \begin{bmatrix} 2 & 0.8 \\ 0.8 & 1 \end{bmatrix}$
- The contours of the *conditional pdf* $p^{x_2}(x_1, x_2)$ as a function of x_1 and x_2 are shown in blue.
- Both confidence ellipsoids and conditional contours correspond to confidence levels of 0.1, 0.3, 0.5, 0.7, 0.9
- The conditional pdf is constant on lines $x_1 = \Sigma_{12}\Sigma_{22}^{-1}x_2 + a$



Conditional confidence intervals

Compare with the marginal pdf confidence intervals



Notice that conditional confidence intervals are narrower, since $T = \Sigma_{11} - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21}$ hence $T \leq \Sigma_{11}$, i.e., measuring x_2 gives *information* about x_1

Independence

suppose $x : \Omega \rightarrow s\mathbb{R}^n$ is a random variable with induced pdf $p^x : \mathbb{R}^n \rightarrow \mathbb{R}$

$$x = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

each component x_i is a random variable, with *marginal pdf* $p^{x_i} : \mathbb{R} \rightarrow \mathbb{R}$ given by integrating over all other components, e.g. in \mathbb{R}^3 ,

$$p^{x_3}(x_3) = \int_{x_2=-\infty}^{\infty} \int_{x_1=-\infty}^{\infty} p^x(x) dx_1 dx_2$$

random variables $x_1, \dots, x_n \in \mathbb{R}$ are called *independent* if

$$p^x(x) = p^{x_1}(x_1)p^{x_2}(x_2) \dots p^{x_n}(x_n)$$

Adding independent random variables

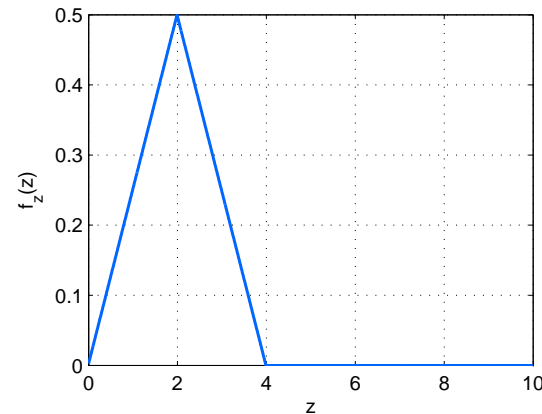
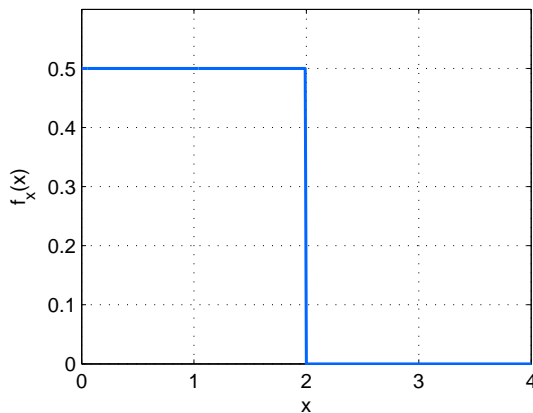
$x, y \in \mathbb{R}$ are *independent* random variables, with induced pdf's p^x and p^y

let $z = x + y$; the induced pdf of z is the *convolution* of p^x and p^y

$$p^z(z) = \int_{-\infty}^{\infty} p^x(x)p^y(z - x) dx$$

example: convolution of a uniform pdf with itself

if x, y are both uniform on $[0, 2]$, and independent, let $z = x + y$



the distribution of the sum of two uniform rv's is not uniform.

Uncorrelated Gaussians

Uncorrelated Gaussians are independent

Suppose $x : \Omega \rightarrow \mathbb{R}^n$. If $x \sim \mathcal{N}(\mu, \Sigma)$ and $\Sigma_{12} = 0$, then x_1 and x_2 are independent.

To see this, notice that

$$\begin{aligned} p^x(x_1, x_2) &= c_1 \exp\left(-\frac{1}{2}x^T \Sigma^{-1}x\right) \\ &= c_1 \exp\left(-\frac{1}{2}x_1^T \Sigma_{11}^{-1}x_1\right) \exp\left(-\frac{1}{2}x_2^T \Sigma_{22}^{-1}x_2\right) \\ &= p^{x_1}(x_1)p^{x_2}(x_2) \end{aligned}$$

where p^{x_1} and p^{x_2} are Gaussian pdfs.

Example: correlation

Suppose $x \sim \mathcal{N}(0, \Sigma)$ where

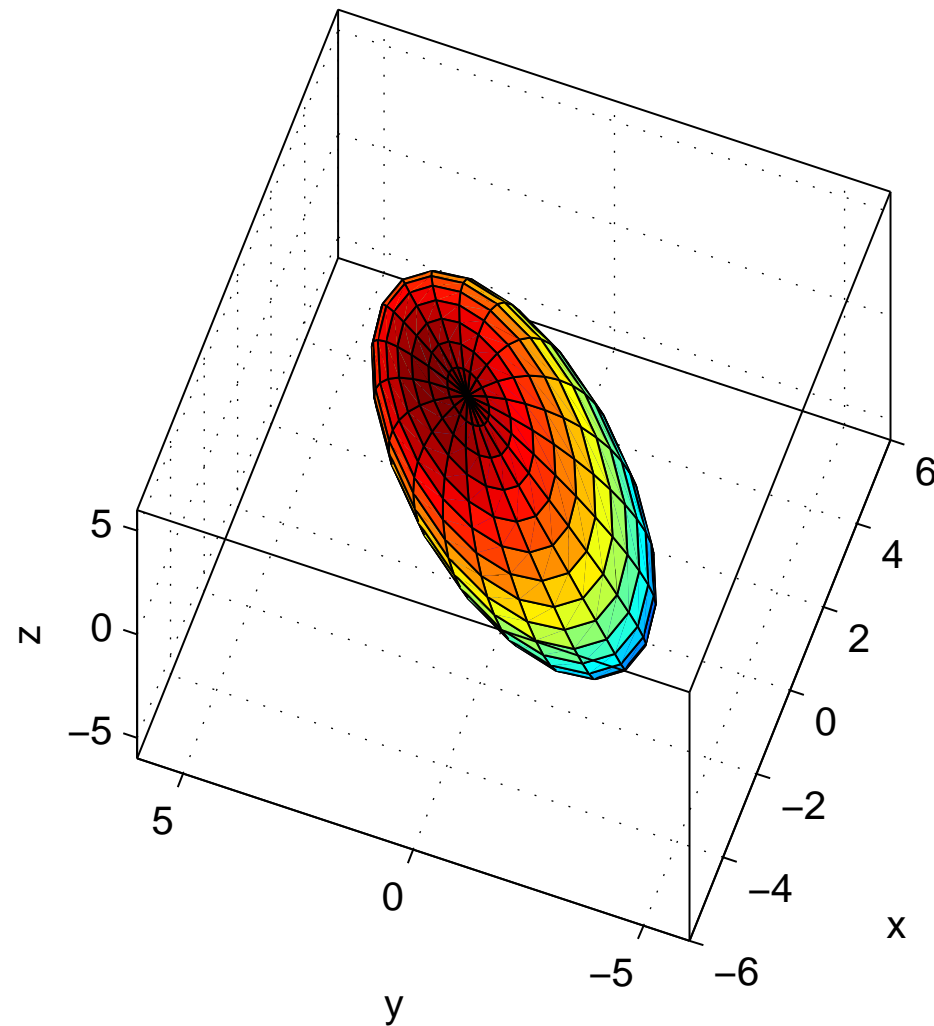
$$\Sigma = \begin{bmatrix} 2 & 1 & 0 \\ 1 & 2 & 1 \\ 0 & 1 & 2 \end{bmatrix}$$

Then

- x and y are correlated
- z and y are correlated
- z and x are uncorrelated
- The eigenvalues of Σ are 0.59, 2, 3.4

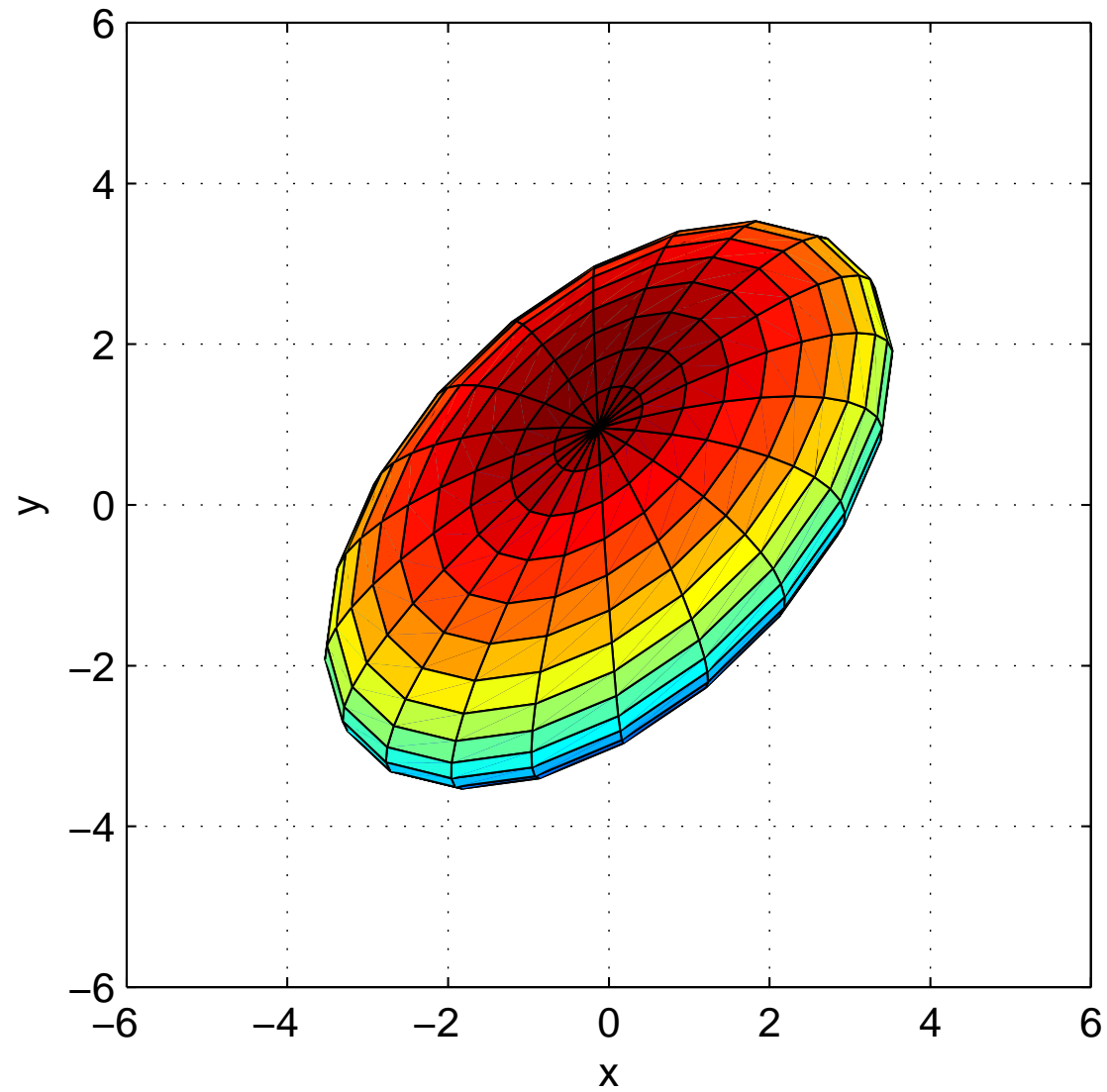
Example: correlation

The 90% confidence ellipsoid is



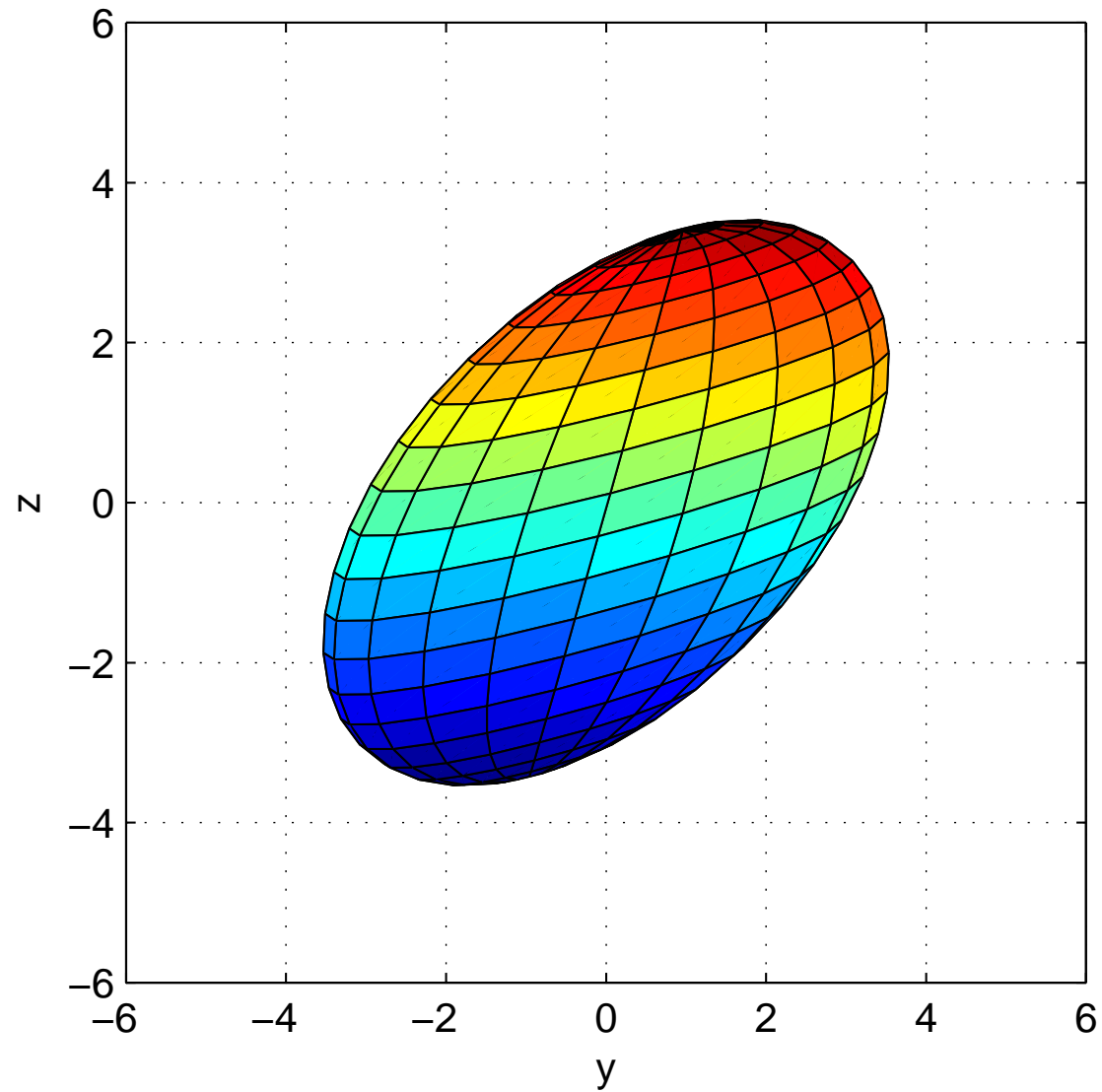
Example: correlation

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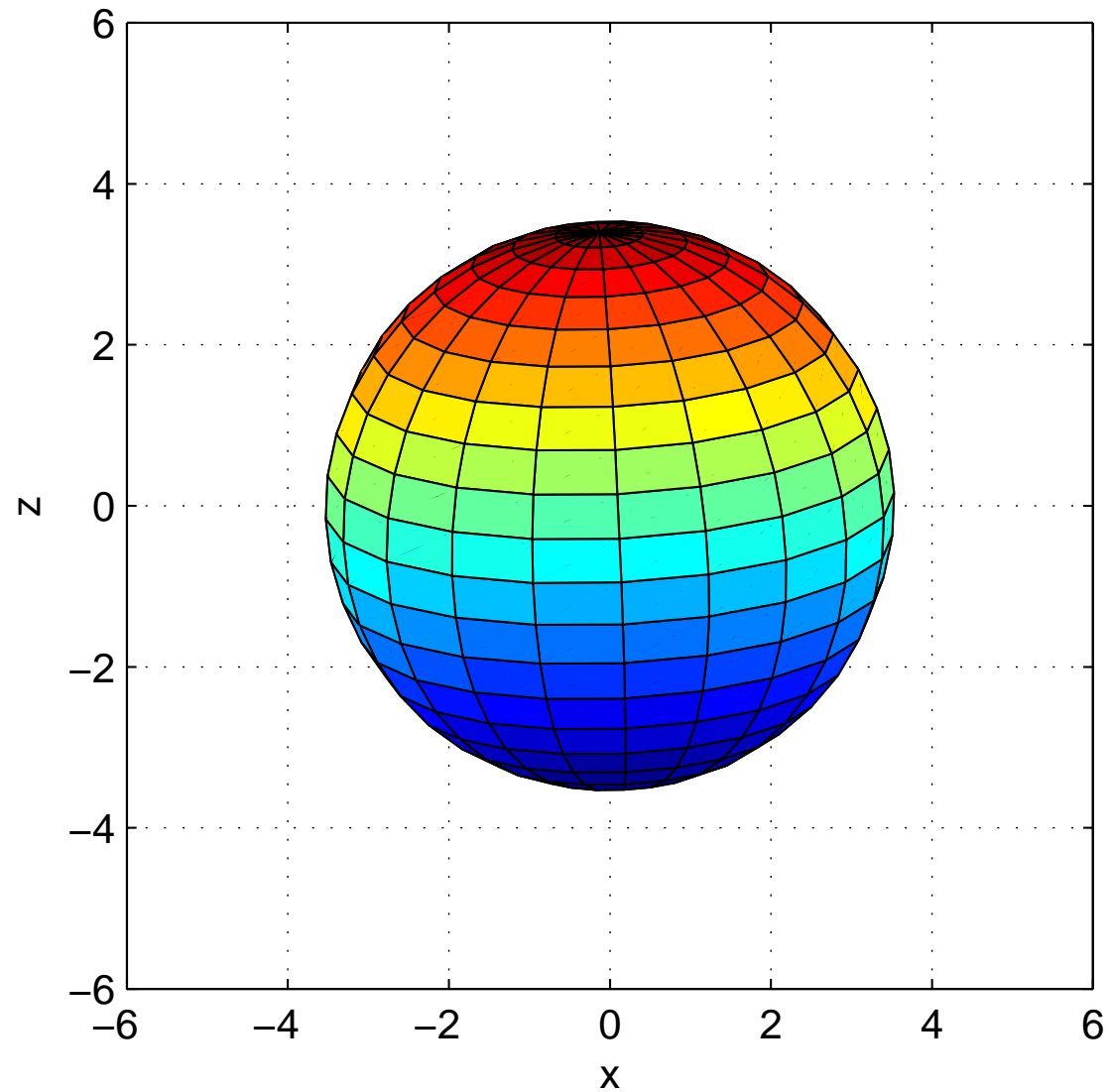
Example: correlation

The 90% confidence ellipsoid is



Example: correlation

The 90% confidence ellipsoid is



example: adding Gaussian random vectors

suppose $x \in \mathbb{R}^2$, and $x \sim \mathcal{N}(\mu, \Sigma)$; let

$$\begin{aligned} z &= \begin{bmatrix} 1 & 1 \end{bmatrix} x \\ &= x_1 + x_2 \end{aligned}$$

then

$$\mathbf{E} z = \mu_1 + \mu_2$$

and

$$\mathbf{cov}(z) = \begin{bmatrix} 1 & 1 \end{bmatrix} \Sigma \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

if $\Sigma = \begin{bmatrix} \Sigma_{11} & 0 \\ 0 & \Sigma_{22} \end{bmatrix}$ is diagonal, so x_1 and x_2 are independent, then

$$\mathbf{cov}(z) = \Sigma_{11} + \Sigma_{22}$$