

## 10 Factorization

### 10.1 State-Space Factorization

We have the simplest factorization result below. First, recall the product realization

$$\left[ \begin{array}{c|c} A_1 & B_1 \\ \hline C_1 & D_1 \end{array} \right] \left[ \begin{array}{c|c} A_2 & B_2 \\ \hline C_2 & D_2 \end{array} \right] = \left[ \begin{array}{cc|c} A_2 & 0 & B_2 \\ B_1C_2 & A_1 & B_1D_2 \\ \hline D_1C_2 & C_1 & D_1D_2 \end{array} \right] = \left[ \begin{array}{cc|c} A_1 & B_1C_2 & B_1D_2 \\ 0 & A_2 & B_2 \\ \hline C_1 & D_1C_2 & D_1D_2 \end{array} \right]$$

**Lemma 1.** *Suppose*

$$G = \left[ \begin{array}{cc|c} A_{11} & A_{12} & B_1 \\ A_{21} & A_{22} & B_2 \\ \hline C_1 & C_2 & D \end{array} \right] \quad H_1 = \left[ \begin{array}{c|c} A_{22} & B_2D_2^{-1} \\ \hline C_2 & D_1 \end{array} \right] \quad H_2 = \left[ \begin{array}{c|c} A_{11} & B_1 \\ \hline D_1^{-1}C_1 & D_2 \end{array} \right]$$

where  $D$  is invertible and  $D = D_1D_2$ . Let  $A^\times$  be the generator for  $G^{-1}$  in the same coordinates as  $G$ , that is  $A^\times = A - BD^{-1}C$ . If

$$A_{12} = 0 \quad \text{and} \quad A_{21}^\times = 0$$

then

$$G = H_1H_2$$

**Proof.** This is immediate, since

$$A^\times = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} - \begin{bmatrix} B_1 \\ B_2 \end{bmatrix} D^{-1} [C_1 \quad C_2]$$

and

$$H_1H_2 = \left[ \begin{array}{cc|c} A_{11} & 0 & B_1 \\ B_2D_2^{-1}C_1 & A_{22} & B_2 \\ \hline C_1 & C_2 & D \end{array} \right]$$

■

Notice in particular that this means that if

$$\text{range} \begin{bmatrix} 0 \\ I \end{bmatrix} \text{ is } A\text{-invariant}$$

and

$$\text{range} \begin{bmatrix} I \\ 0 \end{bmatrix} \text{ is } A^\times\text{-invariant}$$

then it is easy to factorize  $G$ . We also have

$$H_1^{-1} = \left[ \begin{array}{c|c} A_{22} - B_2D_2^{-1}C_2 & -B_2D_2^{-1} \\ \hline D_1^{-1}C_2 & D_1^{-1} \end{array} \right] \quad H_2^{-1} = \left[ \begin{array}{c|c} A_{11} - B_1D_2^{-1}C_1 & -B_1D_2^{-1} \\ \hline D_2^{-1}C_1 & D_2^{-1} \end{array} \right]$$

Another version of Lemma 1 is below.

**Lemma 2.** *Suppose*

$$G = \left[ \begin{array}{cc|c} A_{11} & A_{12} & B_1 \\ A_{21} & A_{22} & B_2 \\ \hline C_1 & C_2 & D \end{array} \right] \quad H_1 = \left[ \begin{array}{c|c} A_{11} & B_1 D_2^{-1} \\ \hline C_1 & D_1 \end{array} \right] \quad H_2 = \left[ \begin{array}{c|c} A_{22} & B_2 \\ \hline D_1^{-1} C_2 & D_2 \end{array} \right]$$

and  $D = D_1 D_2$ . Let  $A^\times$  be the generator for  $G^{-1}$ , that is  $A^\times = A - B D^{-1} C$ . If  $A_{21} = 0$  and  $A_{12}^\times = 0$  then  $G = H_1 H_2$ .

More generally, we would like to change coordinates to achieve the conditions required by Lemma 1, that is  $A_{12} = 0$  and  $A_{21}^\times = 0$ . In other words, we need coordinates in which  $A^\times$  is upper triangular, and this corresponds to finding a subspace  $V$  which is  $A^\times$  invariant. We also need those coordinates to be such that  $A$  is lower triangular.

Suppose  $A_{11}$  and  $A_{22}$  are  $n \times n$ . Then we need  $V$  to be at least  $n$  dimensional, since we need  $A_{21}^\times = 0$ . Suppose  $V$  is given by

$$V = \text{range } T_1$$

We will use a change of coordinates

$$T = [T_1 \quad T_2]$$

then under this coordinate change  $A^\times$  will be upper triangular if  $V$  is  $A^\times$ -invariant.

However, we also need  $A$  to be lower triangular in these new coordinates, and so we need  $\text{range } T_2$  to be  $A$ -invariant. One choice of  $T_2$  which will satisfy this is

$$T_2 = \begin{bmatrix} 0 \\ I \end{bmatrix}$$

since  $A$  is lower triangular. These two subspaces must be complementary, that is

$$\text{range } T_1 \oplus \text{range} \begin{bmatrix} 0 \\ I \end{bmatrix} = \mathbb{R}^{2n}$$

and this holds if and only if  $T$  will be invertible. Let

$$T_1 = \begin{bmatrix} P_1 \\ P_2 \end{bmatrix}$$

Then  $T$  is invertible if and only if  $P_1$  is invertible. Then

$$\text{range} \begin{bmatrix} P_1 \\ P_2 \end{bmatrix} = \text{range} \begin{bmatrix} I \\ P_2 P_1^{-1} \end{bmatrix}$$

So we choose

$$T = \begin{bmatrix} I & 0 \\ P & I \end{bmatrix}$$

This motivates the following problem.

**Lemma 3.** *Suppose  $V \subset \mathbb{R}^n$  is an  $n$ -dimensional subspace. Then*

$$V \oplus \text{range} \begin{bmatrix} 0 \\ I \end{bmatrix} = \mathbb{R}^{2n} \quad \text{and } V \text{ is } A^\times\text{-invariant}$$

*if and only if there exists  $P$  such that*

$$V = \text{range} \begin{bmatrix} I \\ P \end{bmatrix}$$

*and*

$$\begin{bmatrix} I & 0 \\ -P & I \end{bmatrix} A^\times \begin{bmatrix} I & 0 \\ P & I \end{bmatrix} \text{ is block lower triangular}$$

Now let

$$A^\times = \begin{bmatrix} A_{11}^\times & A_{12}^\times \\ A_{21}^\times & A_{22}^\times \end{bmatrix} \quad T = \begin{bmatrix} I & 0 \\ P & I \end{bmatrix}$$

Then

$$T^{-1}A^\times T = \begin{bmatrix} A_{11}^\times + A_{12}^\times P & A_{12}^\times \\ -PA_{11}^\times + A_{21}^\times - PA_{12}^\times P + A_{22}^\times P & -PA_{12}^\times + A_{22}^\times \end{bmatrix}$$

and then  $A_{21}^\times = 0$  if

$$-PA_{11}^\times + A_{21}^\times - PA_{12}^\times P + A_{22}^\times P = 0$$

This equation is called the ***Riccati*** equation. Note that we can also write the Riccati equation as

$$\begin{bmatrix} -P & I \end{bmatrix} A^\times \begin{bmatrix} I \\ P \end{bmatrix} = 0$$

Let's summarize so far.

**Theorem 4.** *Suppose*

$$G = \left[ \begin{array}{cc|c} A_{11} & 0 & B_1 \\ A_{21} & A_{22} & B_2 \\ \hline C_1 & C_2 & D \end{array} \right]$$

*where  $D$  is invertible. Let  $A^\times = A - BD^{-1}C$ , and suppose  $P$  satisfies the Riccati equation*

$$\begin{bmatrix} -P & I \end{bmatrix} A^\times \begin{bmatrix} I \\ P \end{bmatrix} = 0$$

*Let  $D_1 D_2 = D$  and*

$$H_1 = \left[ \begin{array}{c|c} A_{22} & (-PB_1 + B_2)D_2^{-1} \\ \hline C_2 & D_1 \end{array} \right] \quad H_2 = \left[ \begin{array}{c|c} A_{11} & B_1 \\ \hline D_1^{-1}(C_1 + C_2P) & D_2 \end{array} \right]$$

*Then  $G = H_1 H_2$ .*

**Proof.** To prove this, we use coordinates

$$T = \begin{bmatrix} I & 0 \\ P & I \end{bmatrix}$$

then

$$G = \left[ \begin{array}{cc|c} A_{11} & 0 & B_1 \\ -PA_{11} + A_{21} + A_{22}P & A_{22} & -PB_1 + B_2 \\ \hline C_1 + C_2P & C_2 & D \end{array} \right]$$

and

$$\begin{aligned} T^{-1}A^\times T &= \begin{bmatrix} A_{11}^\times + A_{12}^\times P & A_{12}^\times \\ -PA_{11}^\times + A_{21}^\times - PA_{12}^\times P + A_{22}^\times P & -PA_{12}^\times + A_{22}^\times \end{bmatrix} \\ &= \begin{bmatrix} A_{11}^\times + A_{12}^\times P & A_{12}^\times \\ 0 & -PA_{12}^\times + A_{22}^\times \end{bmatrix} \end{aligned}$$

Then Lemma 1 gives the desired result. ■

## 10.2 Spectral Factorization

We'll need the following expressions for rational functions. This is simply algebraic manipulation.

**Lemma 5.** *Suppose  $G(z) = C(zI - A)^{-1}B + D$  and  $A$  is invertible. Then*

$$\begin{aligned} \tilde{G}(z) &= D^T + B^T(z^{-1}I - A)^{-1}C^T \\ &= \left[ \begin{array}{c|c} A^{-T} & -A^{-T}C^T \\ \hline B^T A^{-T} & D^T - B^T A^{-T}C^T \end{array} \right] (z) \end{aligned}$$

and

$$\tilde{G}G = \left[ \begin{array}{cc|c} A & 0 & B \\ -A^{-T}C^T C & A^{-T} & -A^{-T}C^T D \\ \hline D^T C - B^T A^{-T}C^T C & B^T A^{-T} & D^T D - B^T A^{-T}C^T D \end{array} \right]$$

**Proof.** By definition

$$\tilde{G}(z) = D^T + B^T(z^{-1}I - A)^{-1}C^T$$

and we need to express the rational  $(z^{-1}I - A)^{-1}$  in terms of  $(zI - Q)^{-1}$  for some  $Q$ . We have

$$z(zI - A)^{-1} = I + (zI - A)^{-1}A$$

and hence

$$(z^{-1}I - A^T)^{-1} = -A^{-T}(I + (zI - A^{-T})^{-1}A^{-T})$$

This immediately gives the first result. The second result follows from the usual product expression. ■

We'd like to use our previous factorization results to construct the spectral factorization of  $\tilde{G}G$ . Assume for simplicity that  $C^T D = 0$  and  $D^T D > 0$ , and let  $H$  be the generator matrix for a realization of  $(\tilde{G}G)^{-1}$  so that

$$H = \begin{bmatrix} A & 0 \\ -A^{-T}C^T C & A^{-T} \end{bmatrix} - \begin{bmatrix} B \\ 0 \end{bmatrix} (D^T D)^{-1} [-B^T A^{-T} C^T C \quad B^T A^{-T}]$$

Define for convenience

$$Q = C^T C \quad R = D^T D \quad G = BR^{-1}B^T$$

then

$$H = \begin{bmatrix} A + GA^{-T}Q & -GA^{-T} \\ -A^{-T}Q & A^{-T} \end{bmatrix} \quad (1)$$

Also define

$$J = \begin{bmatrix} 0 & -I \\ I & 0 \end{bmatrix}$$

Then the matrix  $H$  satisfies

$$J^{-1}H^T J = J^{-1}$$

Such matrices are called *symplectic*. This implies that  $H$  is similar to  $H^{-T}$ , and therefore if  $\lambda$  is an eigenvalue of  $H$  so is  $1/\bar{\lambda}$ . One can show that every symplectic matrix has the form of equation (1).

### 10.2.1 The Riccati Equation

We'd like to apply Theorem 4 to factorize  $\tilde{G}G$ . The corresponding Riccati equation is

$$[-P \quad I] H \begin{bmatrix} I \\ P \end{bmatrix} = 0$$

which is just

$$-PA + (I + PG)A^{-T}(P - Q) = 0$$

**Lemma 6.** *Suppose  $A$  is invertible and  $P$  satisfies the Riccati equation*

$$[-P \quad I] H \begin{bmatrix} I \\ P \end{bmatrix} = 0$$

*then  $I + PG$  is invertible.*

**Proof.** Suppose  $I + PG$  is not invertible. Then there exists  $v \neq 0$  such that  $v^T(I + PG) = 0$ . Then, using the Riccati equation, we have

$$v^T(-PA + (I + PG)A^{-T}(P - Q)) = 0$$

Then by assumption  $v^T(I + PG) = 0$  and so

$$v^T P A = 0$$

and since  $A$  is invertible we have  $v^T P = 0$ . But again, since  $v^T(I + PG) = 0$  this implies  $v = 0$ , which is a contradiction. ■

We can write the Riccati equation in several different ways

- $-PA + (I + PG)A^{-T}(P - Q) = 0$
- $A^T(I + PG)^{-1}PA - P + Q = 0$
- $A^T PA - P - A^T PG(I + PG)^{-1}PA + Q = 0$
- $A^T PA - P - A^T PB(R + B^T PB)^{-1}B^T PA + Q = 0$

which are easily seen to be equivalent.

**Theorem 7.** *Suppose*

$$G = \left[ \begin{array}{c|c} A & B \\ \hline C & D \end{array} \right]$$

with  $A$  invertible, and  $D^T D > 0$  and  $C^T D = 0$ . Let  $Q = C^T C$  and  $R = D^T D$  and suppose  $P$  satisfies the Riccati equation

$$A^T PA - P - A^T PB(R + B^T PB)^{-1}B^T PA + Q = 0$$

and let  $D_1 D_2 = D^T D$  and

$$H_1 = \left[ \begin{array}{c|c} A^{-T} & -PBD_2^{-1} \\ \hline B^T A^{-T} & D_1 \end{array} \right] \quad H_2 = \left[ \begin{array}{c|c} A & B \\ \hline D_1^{-1} B^T A^{-T}(P - Q) & D_2 \end{array} \right]$$

Then  $\tilde{G}G = H_1 H_2$ .

**Proof.** This follows by applying Theorem 4 to the realization of  $\tilde{G}G$  given by Lemma 5.

■

**Theorem 8.** *Suppose*

$$G = \left[ \begin{array}{c|c} A & B \\ \hline C & D \end{array} \right]$$

with  $A$  invertible, and  $D^T D > 0$  and  $C^T D = 0$ . Let  $Q = C^T C$  and  $R = D^T D$ , and suppose  $P$  satisfies the Riccati equation

$$A^T PA - P - A^T PB(R + B^T PB)^{-1}B^T PA + Q = 0$$

Then let  $W = R + B^T PB$  and

$$H_2 = \left[ \begin{array}{c|c} A & B \\ \hline W^{-\frac{1}{2}} B^T PA & W^{\frac{1}{2}} \end{array} \right]$$

Then  $\tilde{G}G = \tilde{H}_2 H_2$ . Furthermore

$$H_2^{-1} = \left[ \begin{array}{c|c} A - BW^{-1}B^T PA & -BW^{-\frac{1}{2}} \\ \hline W^{-1}B^T PA & W^{-\frac{1}{2}} \end{array} \right]$$

**Proof.** This is shown simply by picking  $D_1 = RW^{-\frac{1}{2}}$  and  $D_2 = W^{\frac{1}{2}}$  and applying Theorem 7. We have

$$\tilde{H} = \left[ \begin{array}{c|c} A^{-T} & -PBW^{-\frac{1}{2}} \\ \hline B^T A^{-T} & W^{\frac{1}{2}} - B^T PBW^{-\frac{1}{2}} \end{array} \right]$$

and we need to show that  $H = H_2$  and  $\tilde{H} = H_1$ . To show that  $H = H_2$ , we only need to check the ‘C’ term, which is

$$\begin{aligned} D_1^{-1}(-B^T A^{-T} C^T C + B^T A^{-T} P) &= D_1^{-1} B^T A^{-T} (P - Q) \\ &= D_1^{-1} B^T (I + PG) PA \\ &= D_1^{-1} B^T (I + PBR^{-1} B^T)^{-1} PA \\ &= D_1^{-1} (I + B^T PBR^{-1})^{-1} B^T PA \\ &= D_1^{-1} R (R + B^T PB)^{-1} B^T PA \\ &= D_1^{-1} RW^{-1} B^T PA \\ &= W^{-\frac{1}{2}} B^T PA \end{aligned}$$

as desired. To show that  $\tilde{H} = H_1$  we only need to check the ‘D’ term, which is

$$\begin{aligned} W^{\frac{1}{2}} - B^T PBW^{-\frac{1}{2}} &= (W - B^T PB)W^{-\frac{1}{2}} \\ &= RW^{-\frac{1}{2}} \\ &= D_1 \end{aligned}$$

as desired. ■

If  $P$  satisfies the Riccati equation, then  $\text{range} \begin{bmatrix} I \\ P \end{bmatrix}$  is an invariant subspace of the Hamiltonian  $H$ . Defining

$$\hat{H} = \begin{bmatrix} I & 0 \\ -P & I \end{bmatrix} H \begin{bmatrix} I & 0 \\ P & I \end{bmatrix}$$

and the Hamiltonian is the generator matrix for  $(\tilde{G}G)^{-1}$ . So as in the factorization Lemma 1, the inverse of  $H_2$  has a generator matrix given by  $\hat{H}_{11}$ . Specifically, from Theorem 8

$$H_2^{-1} = \left[ \begin{array}{c|c} A - BW^{-1} B^T PA & -BW^{-\frac{1}{2}} \\ \hline W^{-1} B^T PA & W^{-\frac{1}{2}} \end{array} \right]$$

Simple algebra, and using the Riccati equation, gives

$$\begin{aligned} \hat{H}_{11} &= A + GA^{-T} (P - Q) \\ &= A - G(I + PG)^{-1} PA \\ &= (I + GP)^{-1} A \end{aligned}$$

and using  $G = BR^{-1} B^T$  we have

$$\hat{H}_{11} = A - BW^{-1} B^T PA$$

which, as expected, is the generator matrix of  $H_2^{-1}$ . Also, because  $H$  and  $\hat{H}$  are similar, they have the same eigenvalues, and by the invariant subspace property  $\hat{H}$  is triangular, so the eigenvalues of  $\hat{H}_{11}$  are just a subset of those of  $H$ . Each solution of  $P$  the Riccati equation gives an invariant subspace of  $H$ , and a corresponding subset of the eigenvalues of  $H$  in  $\hat{H}_{11} = (I + GP)^{-1}A$ .

**Lemma 9.** *Suppose  $Q, G$  are symmetric and*

$$H = \begin{bmatrix} A + GA^{-T}Q & -GA^{-T} \\ -A^{-T}Q & A^{-T} \end{bmatrix}$$

and  $H$  has no eigenvalues on the unit circle. Then there is at most one matrix  $P$  satisfying the Riccati equation

$$\begin{bmatrix} -P & I \end{bmatrix} H \begin{bmatrix} I \\ P \end{bmatrix} = 0$$

such that

$$\rho((I + GP)^{-1}A) < 1$$

This solution is called the **stabilizing** solution.

We won't prove this here; for details see Zhou, Doyle and Glover.

**Lemma 10.** *Suppose  $Q, G$  are symmetric and*

$$H = \begin{bmatrix} A + GA^{-T}Q & -GA^{-T} \\ -A^{-T}Q & A^{-T} \end{bmatrix}$$

and  $H$  has no eigenvalues on the unit circle. Then the stabilizing solution  $P$  of the Riccati equation is symmetric.

**Proof.** Let  $T = \begin{bmatrix} I \\ P \end{bmatrix}$ . Then since  $P$  satisfies the Riccati equation, we have

$$HT = T\hat{H}_{11} \tag{2}$$

where  $\hat{H}_{11} = (I + GP)^{-1}A$ . Multiply this equation on the left by  $\hat{H}_{11}^*T^*J$  to give

$$\begin{aligned} \hat{H}_{11}^*T^*JT\hat{H}_{11} &= \hat{H}_{11}^*T^*JHT \\ &= T^*H^*JHT \end{aligned}$$

Since  $H$  is symplectic, we know  $H^T JH = J$ . Hence

$$\hat{H}_{11}^*T^*JT\hat{H}_{11} - T^*JT = 0$$

Let  $V = T^*JT$ . This is a Lyapunov equation in  $V$ , and since  $P$  is by assumption the stabilizing solution, we have  $\hat{H}_{11}$  is stable. Hence the unique solution to the Lyapunov equation  $\hat{H}_{11}^*V\hat{H}_{11} - V = 0$  is  $V = 0$ . Hence  $T^*JT = 0$ , which means  $P = P^*$ . ■

**Lemma 11.** *Suppose  $Q, G$  are symmetric and*

$$H = \begin{bmatrix} A + GA^{-T}Q & -GA^{-T} \\ -A^{-T}Q & A^{-T} \end{bmatrix}$$

and  $H$  has no eigenvalues on the unit circle. Then the stabilizing solution  $P$  of the Riccati equation satisfies  $P \geq 0$ .

See Zhou, Doyle and Glover for a proof.